



# A Biologically Plausible Spiking Neural Model of Eyeblink Conditioning in the Cerebellum

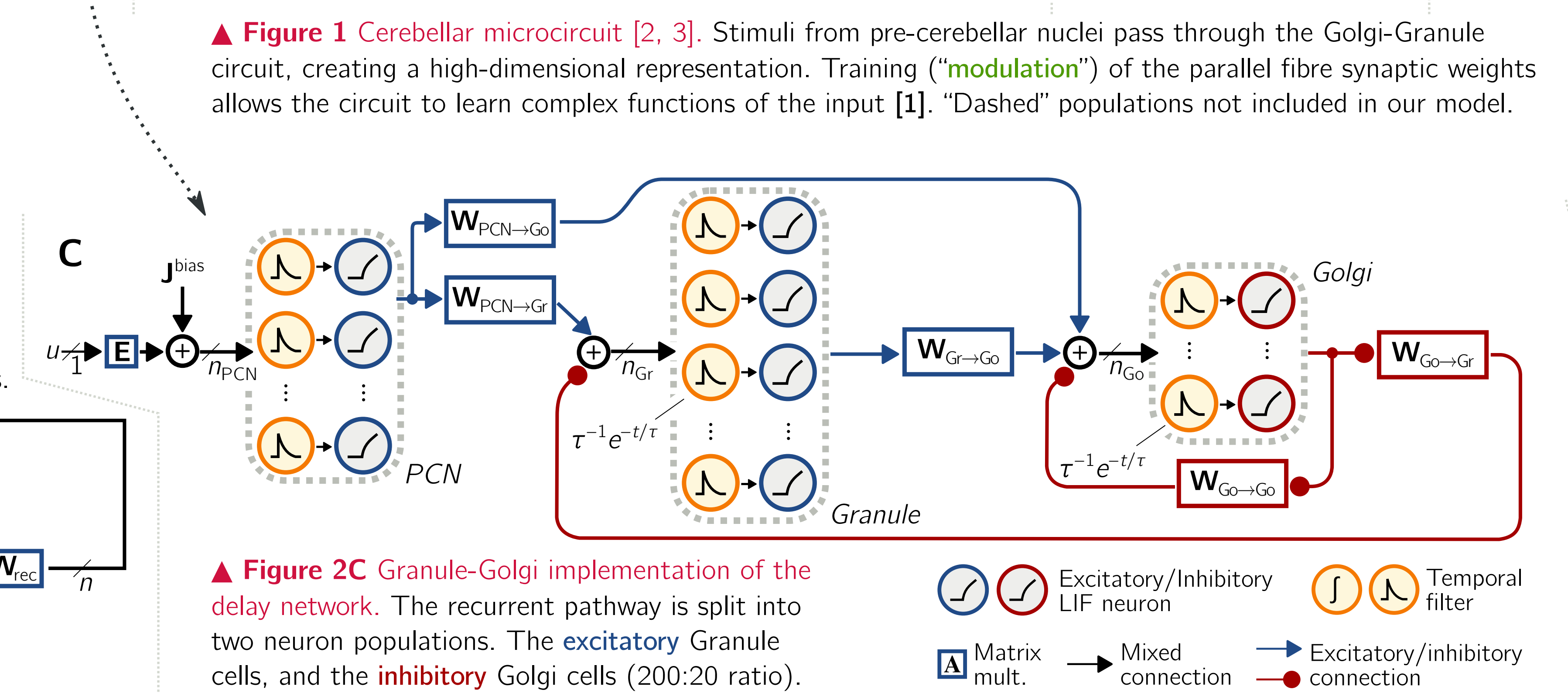
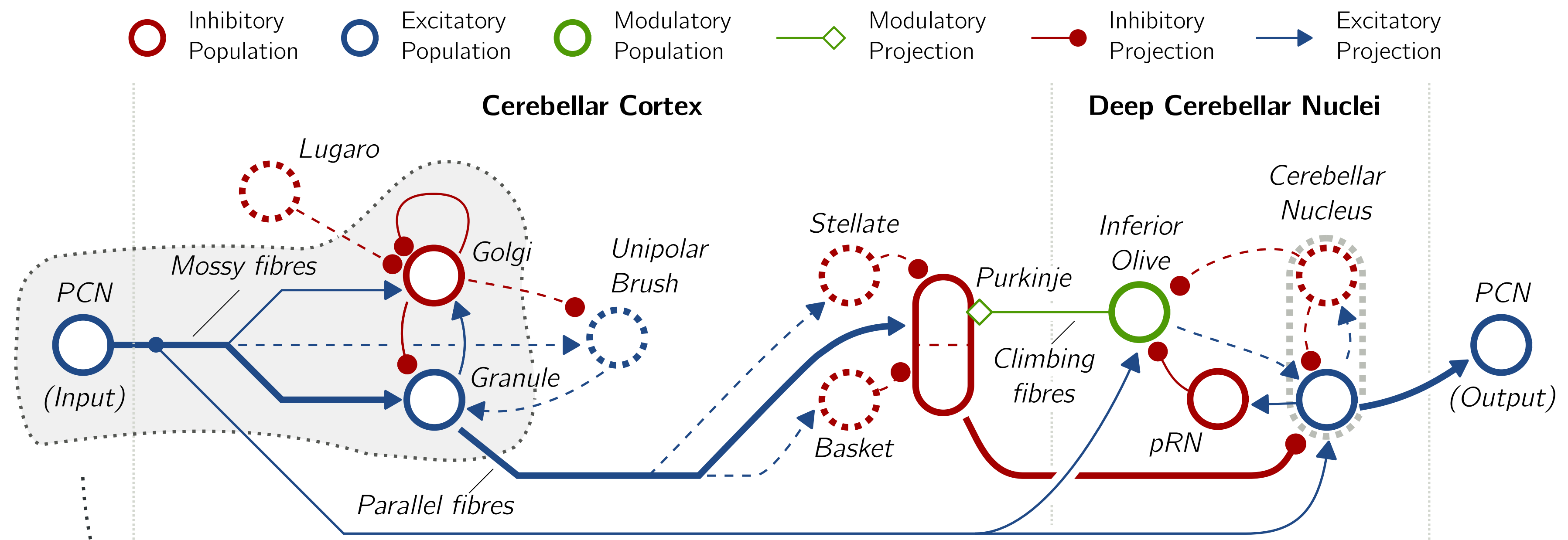
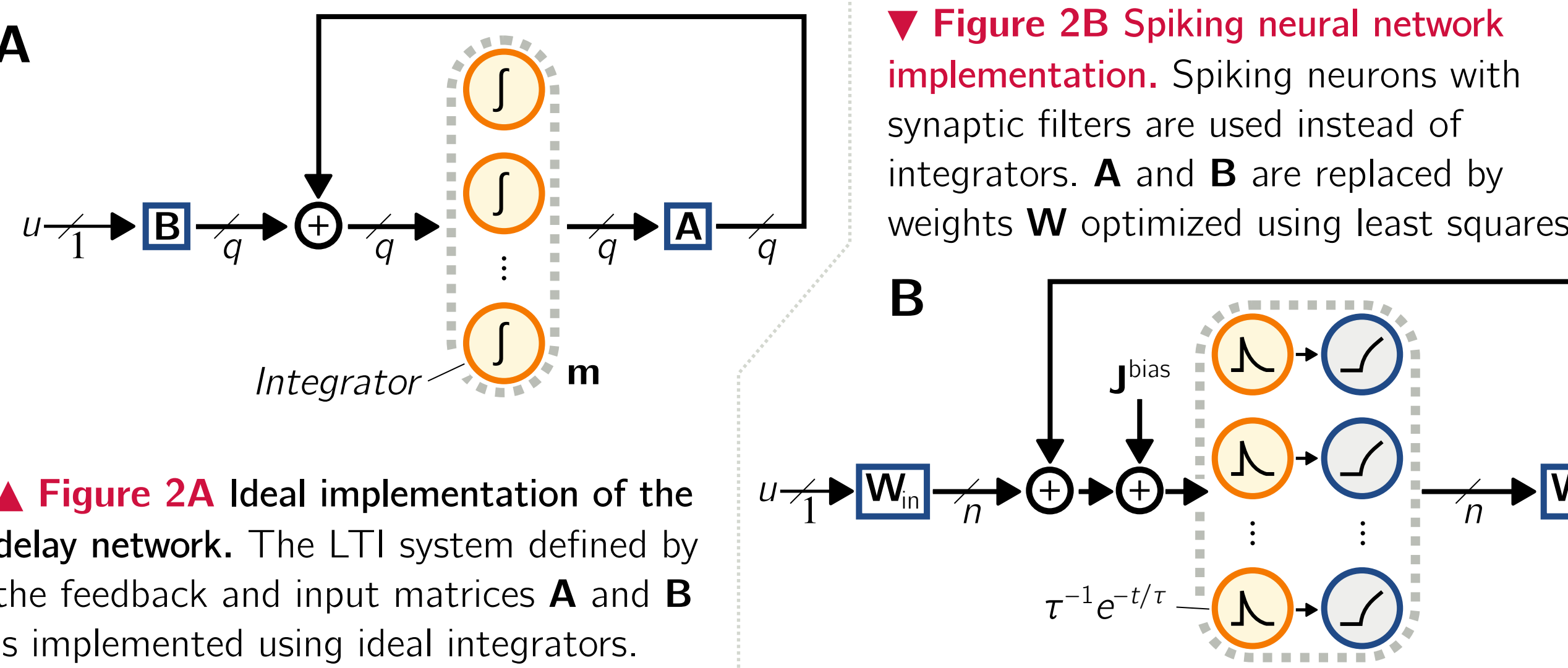
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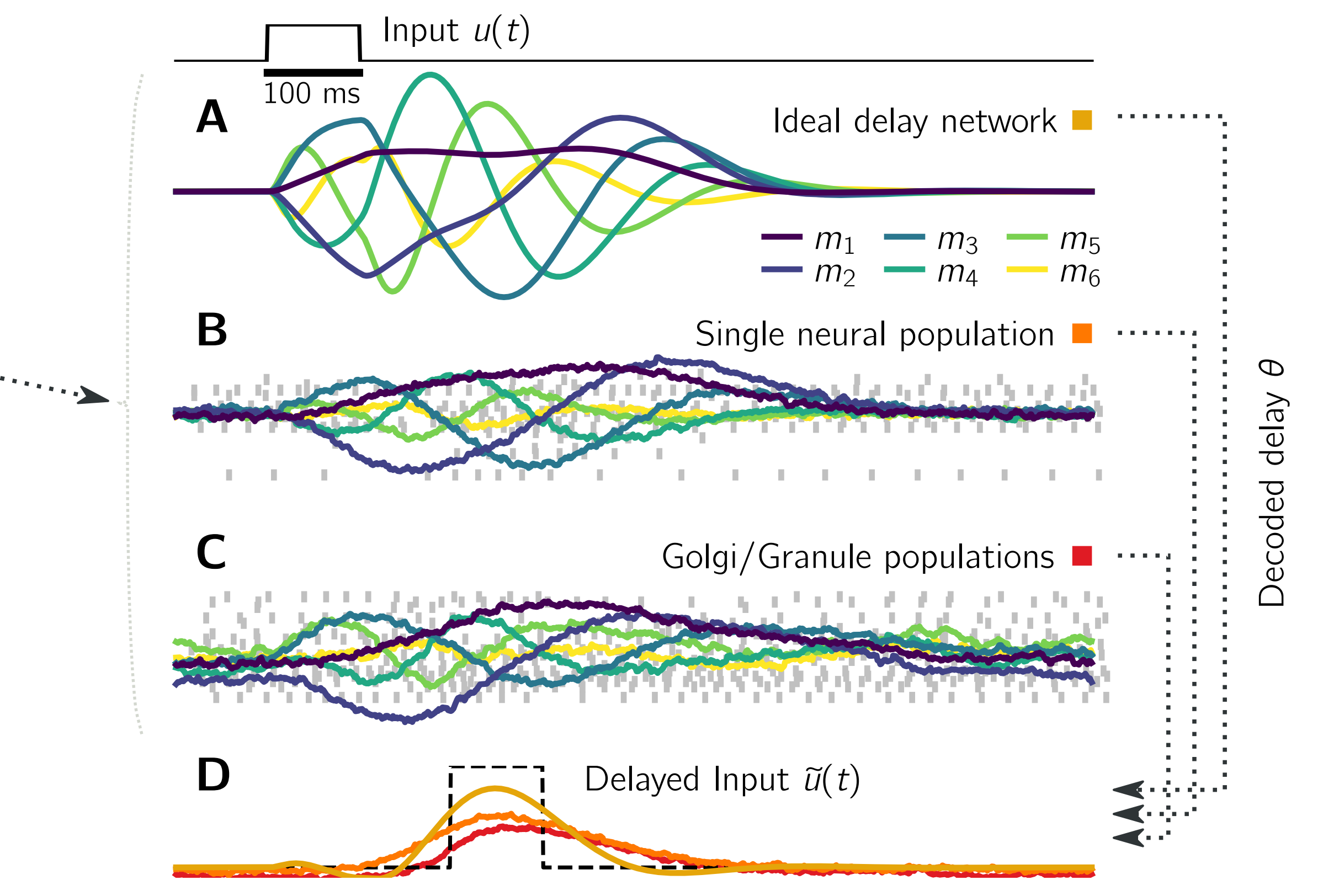
## Introduction 1

- ▶ The Cerebellum is essential for **fine-motor skills** and tasks such as **eyeblink conditioning**.
- ▶ The cerebellum likely supports cognition.
- ▶ Marr suggested functional cerebellar circuitry (Fig. 1; [1]).
- ▶ **This work:** Novel spiking neural model of **eyeblink conditioning** based on **temporal basis** generated in the **Granule-Golgi** circuit.



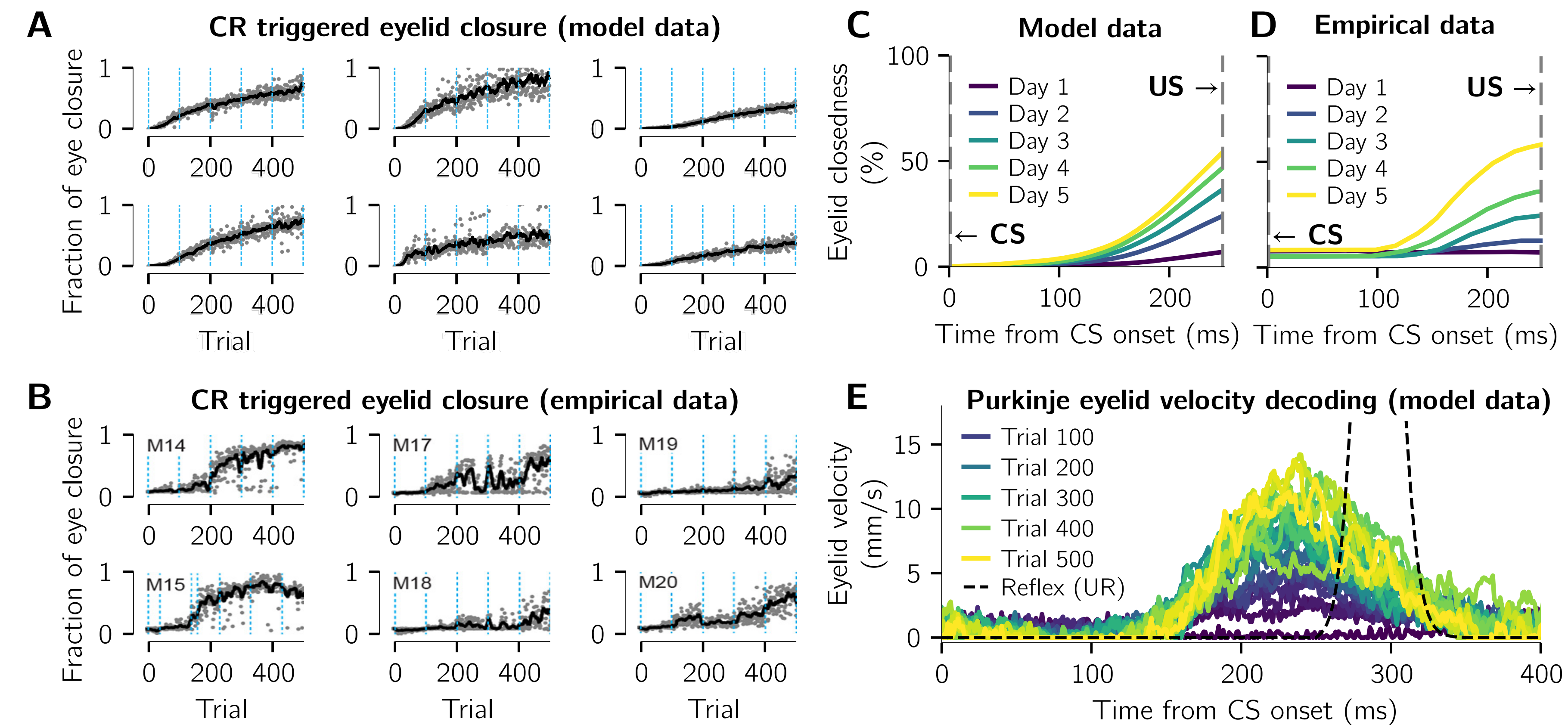
## Methods 2

- ▶ **Goal:** Model that learns to produce CR
- ▶ **Before Training:** Conditioned Stimulus (CS), Uncond. Stim (US), Uncond. Response (UR)
- ▶ **Training:** Shows the learning process with a delay Δ.
- ▶ **After Training:** Shows the learned Conditioned Response (CR).
- ▶ CR ≈ delayed CS ⇒ **Delay Network** [5]
- ▶  $\theta \dot{m} = \mathbf{A}m + \mathbf{B}u$ ,  $\mathbf{A} \in \mathbb{R}^{q \times q}$ ,  $\mathbf{m}, \mathbf{B} \in \mathbb{R}^q$
- ▶ Realize system in Granule-Golgi circuit (Fig. 2)
- ▶ Decode delay Δ by learning the Granule-Purkinje weights online.



## Results 3

- ▶ The Granule-Golgi circuit can implement flexible delays under biological constraints (Dale's principle; time-constants; granule to Golgi ratio; Fig. 3).
- ▶ The learned eyeblink trajectories of our model qualitatively match empirical data (Fig. 4; [4]).
- ▶ Our techniques can be used to construct biologically plausible NEF/SPA models.
- ▶ Model may be used to explore timing-related cognitive phenomena in the cerebellum.



**Figure 4** Simulation results compared to empirical data. (A) CR learned over time as learned by the model. (B) Empirical data for comparison. (C) Shape of the CR relative to the CS onset as learned by the model. (D) Empirical data for comparison. (E) Learned eyelid velocity trajectory decoded from the Purkinje cell activities.

**Figure 3** Delay network representation over time. (A-C) Response to a rectangle input of the three delay network implementations discussed above. Gray lines correspond to individual spikes. (D) Decoding of a delay of θ from the above representations.

**References**

[1] Marr, D. (1969). A theory of cerebellar cortex. *Journal of Physiol.*  
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 [4] Heiney, S. A., Wohl, M. P., Chettih, S. N., Ruffolo, et al. (2014). Cerebellar-dependent expression of motor learning during eyeblink conditioning in head-fixed mice. *Journal of Neuroscience*.  
 [5] Voelker, A. R., & Eliasmith, C. (2018). Improving Spiking Dynamical Networks: Accurate Delays, Higher-Order Synapses, and Time Cells. *Neural Computation*, 30(3).